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Vector components may be expressed as products of the unit vectors with the scalar magnitudes of the vector components. F_x and F_y are referred to as the scalar components of F . $F = F_x i + F_y j$
May resolve a force vector ...

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Eighth Vector Mechanics for Engineers: Statics Edition 3 - 1 How to prepare for the midterm $\hat{=}$ The midterm will be based on Chapters 1-5 and sections 6.1-6.7. It will be one-hour, take-home, open-text book and open-notes exam. ... resultant force vector and a resultant couple vector,

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Seventh Vector Mechanics for Engineers: Dynamics Edition 16 - 7 Axioms of the Mechanics of Rigid Bodies $\hat{=}$ The forces act at different points on a rigid body but but have the same magnitude, direction, and line of action. $\mathbf{F} = F \mathbf{r} / r$ and $\hat{=}$ The forces produce the same moment about any point and are therefore, equipollent external forces.

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Eighth Vector Mechanics for Engineers: Statics Edition 7- 17 Sample Problem 7.3 Draw the shear and
bending moment diagrams for the beam AB. The distributed load of 40 lb/in. extends over 12 in. of the beam,
from A to C, and the 400 lb load is applied at E. SOLUTION:

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because the writers have the amazing ability to turn a simple straightforward idea into an incoherent mess.

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Ferdinand P. Beer & E. Russell Johnston Jr. Vector Mechanics for Engineers (Dynamics) McGraw-Hill Book Company Inc. 1977 (N.B.; book page numbering follows on from companion volume 'Statics') Acrobat 7 Pdf 127.0 Mb.

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Eighth Vector Mechanics for Engineers: Statics Edition Introduction $\hat{\epsilon}$ In preceding chapters, it was assumed that surfaces in contact were either frictionless (surfaces could move freely with respect to each other) or rough (tangential forces prevent relative motion between surfaces). $\hat{\epsilon}$ Actually, no perfectly frictionless surface exists.

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Seventh Vector Mechanics for Engineers: Dynamics Edition 17 - 3 Introduction $\hat{\epsilon}$ Method of work and energy and the method of impulse and momentum will be used to analyze the plane motion of rigid bodies and systems of rigid bodies. $\hat{\epsilon}$ Principle of work and energy is well suited to the solution of problems involving displacements and velocities.

CHAPTER VECTOR MECHANICS FOR ENGINEERS: 17 DYNAMICS

Vector Mechanics for Engineers: Statics dition 7- 22 Sample Problem 7.6 $\hat{\epsilon}$ The change in moment between A and B is equal to area under shear curve between the points. The parabolic shear curve results in a cubic moment curve. $\hat{\epsilon}$ The change in moment between B and C is equal

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